



# Multi-Source Data Driven Outage Detection in Distribution Systems for Decision Support using Probabilistic Graphical Models

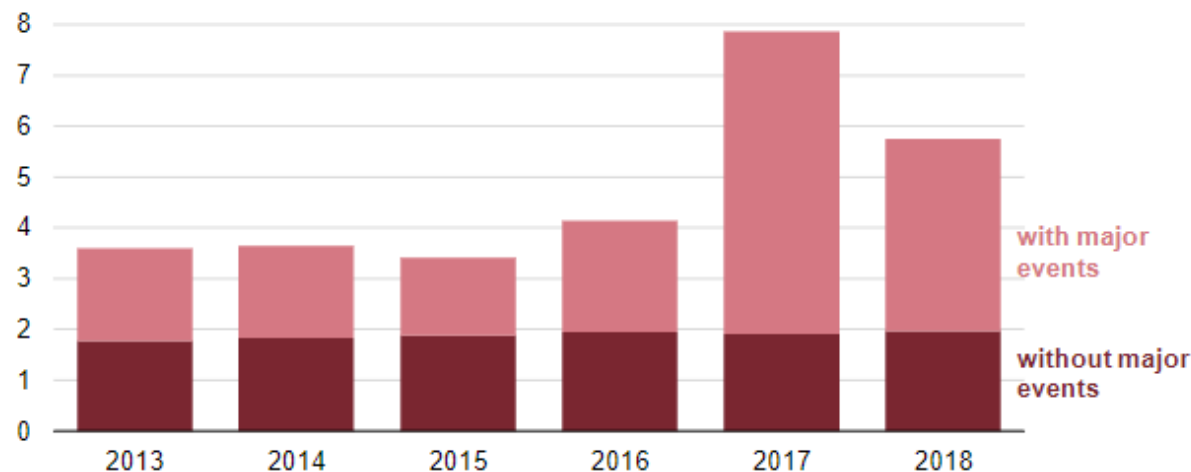
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# Motivation of Data-Driven Outage Location

- Outages can lead to a sharp decline in grid resilience with significant socio-economic losses, which cost an average of about *\$18 billion to \$33 billion per year* in the U.S.
- Outage detection and location is the first task after service disruptions.
- Most utilities still rely on customer reports to track outages, which can cause waste of up to *80% of the invaluable restoration time*. Hence, effective outage detection and location methods are critical to reduce outage duration.

In recent years, customers experienced longer outages.  
 In 2018, each customer lost power for around **5.8 hours**.

**1.9 million** customers in Midwest were affected by 1.4 million outages between August 10 and 13.



# Outage Data Sources

- While SCADA reports main feeder outages, there are multiple data sources that report lateral and grid-edge outages:

| Data Source           | Pros                | Cons  |
|-----------------------|---------------------|---|
| SM last gasp signal   | High accuracy, fast | Limited sensor coverage<br>communication failures |
| Social media data     | Generally available | Misreports, unreliable                            |
| Customer trouble call | Generally available | Low report rate, misreports                       |
| Weather data          | Generally available | Lack of detailed location information             |

- Combing SMs with conventional outage data sources is an ideal solution for outage detection, but it is difficult to achieve because:
  - Heterogeneous characteristics: accuracy levels and reporting rates
  - Partially observable grids with **limited** sensors
  - May provide conflicting or mis-information

# Combining Multiple Data Sources

- This combination means integrating evidences from different data sources as well as different customers:

$$P_{D,C|E}(\mathbf{d}, \mathbf{c}|\mathbf{e}) \quad (1)$$

- ❖  $D$  and  $C$  represent the states of primary network branches and the connections of customers
  - ❖  $E$  is the multi-source evidence set (i.e., trouble call, last gasp signal)
  - ❖ Uppercase: random and evidence variables; lowercase: realization of variables
- Existing methods to solve Eq. 1:
    - Directly solving Eq. 1 using brute-force search over all possible combinations of branch/customer state ([1],[2])
      - **Limitation:** computationally infeasible for large systems
    - Assuming *full independency* among all data sources ([3]-[5])
      - **Limitation:** outage data sources and branches/customers are interdependent

# Outage Location via Probabilistic Graph Learning

✓ Leveraged the conditional independence inherent in distribution grids (rather than the assumed full independence in pooling methods) to encode the distribution network and its data into probabilistic graphs, i.e., *Bayesian networks* (BN) [6]

➤ Node: states of branches/customers and outage data sources. Edge: probabilistic influence of one node on another.

➤ For example, if the utility knows that a customer is in outage, probabilities of receiving SM last gasp signals and trouble calls from that customer will be uncorrelated.

## Advantages:

- ✓ Accurately decompose and efficiently compute Eq. 1
- ✓ Address the problem of insufficient evidences, i.e., low SM coverage or low customer report rates
- ✓ Adaptable to newly added data sources

| Single-source methods | Pooling models                                  | Brute-force search                               | Proposed probabilistic graph  |
|-----------------------|---|--|---|
| $P_{D,C E}(d, c e_1)$ | $\prod P_{D_i E}(d_i e) \prod P_{C_j E}(c_j e)$ | $P_{D,C,E}(\{d_i\}_{i=1}^n, \{c_j\}_{j=1}^m, e)$ | $\frac{\prod P_{D_i D_{i-1}}(d_i d_{i-1}) \prod P_{C_k D_i}(c_k d_i) \prod P_{E_{k,z} C_k}(e_{k,z} c_k)}{\sum_i \sum_k \{\prod P_{D_i D_{i-1}}(d_i d_{i-1}) \prod P_{C_k D_i}(c_k d_i) \prod P_{E_{k,z} C_k}(e_{k,z} c_k)\}} \quad (2)$ |

# Encoding Distribution Grids and Data into Probabilistic Graphs

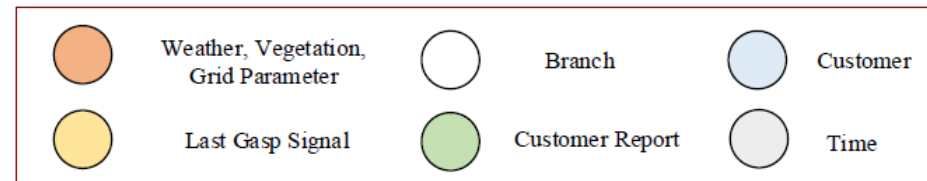
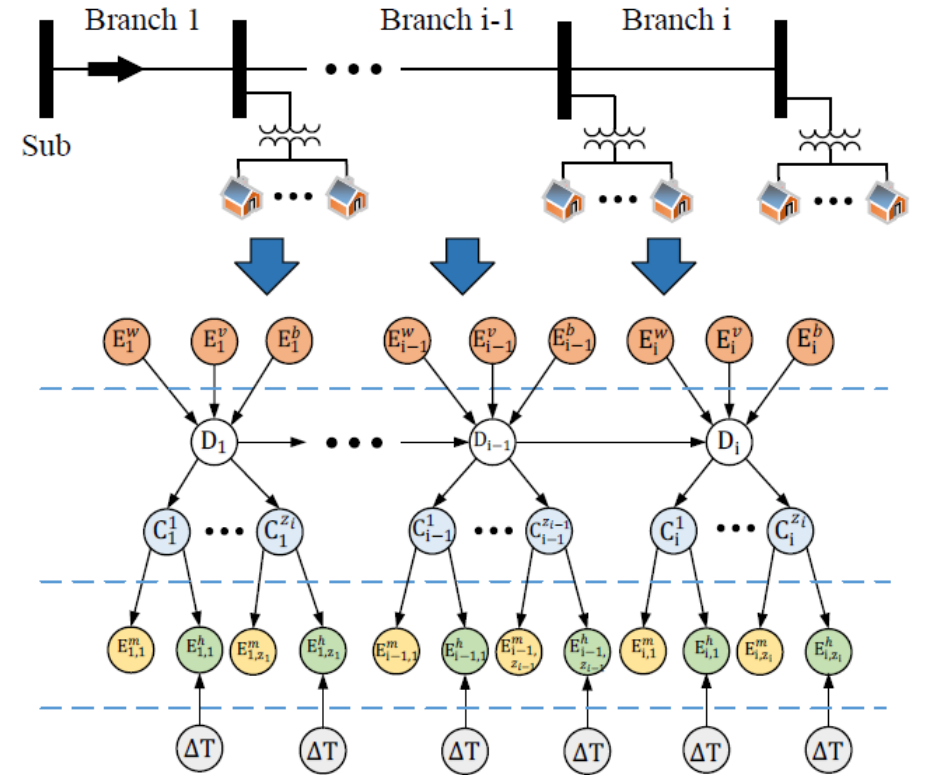
✓ Following these conditional independencies, customers can be modeled as parent nodes for outage data sources in the graph. Putting together these features, a simple directed graph for a radial system can be constructed, as shown in the right figure.

✓  $D_i, C_i^j$ : states of branches/customers

✓  $E_i^w, E_i^v, E_i^b, E_{i,j}^m, E_{i,j}^h, \Delta T$ : outage data sources

✓ Parent variable (variable at the end of the arrow) : the immediate causal source of influence for its child variables (variables pointed by the arrow).

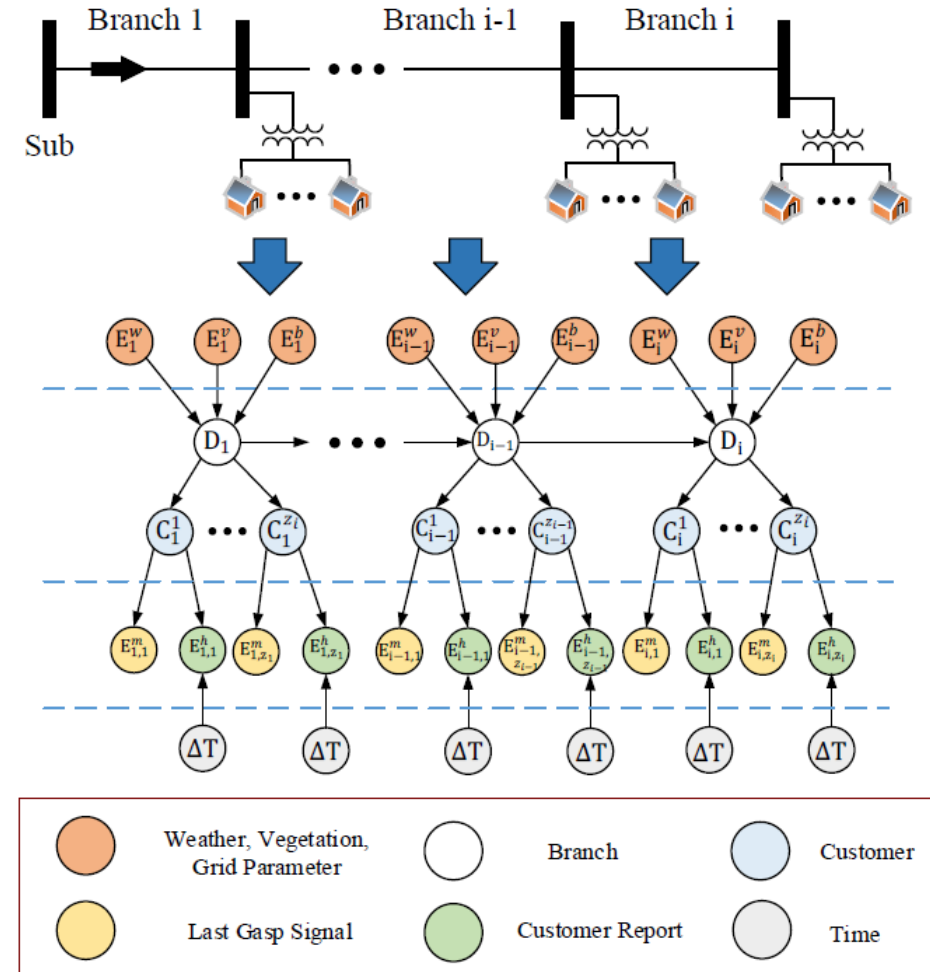
✓ If the values of the parent variables are known, then the child variable becomes conditionally independent of variables that do not directly influence it.



# Encoding Distribution Grids and Data into Probabilistic Graphs

## Salient Features of this Graphical Method:

- ✓ It seamlessly integrates heterogeneous data sources. Different accuracy levels and reporting rates of various sources can be captured by conditional probabilities.
- ✓ It is scalable and adaptive, as new data sources can be directly connected to their parent nodes in the graph without the need to re-learn the structure from scratch. The graph structure can be easily changed if there is a change in network topology.
- ✓ It is robust with respect to misreports and inconsistencies in outage evidences, as uncertainty of each data source is explicitly modeled using graph parameters.

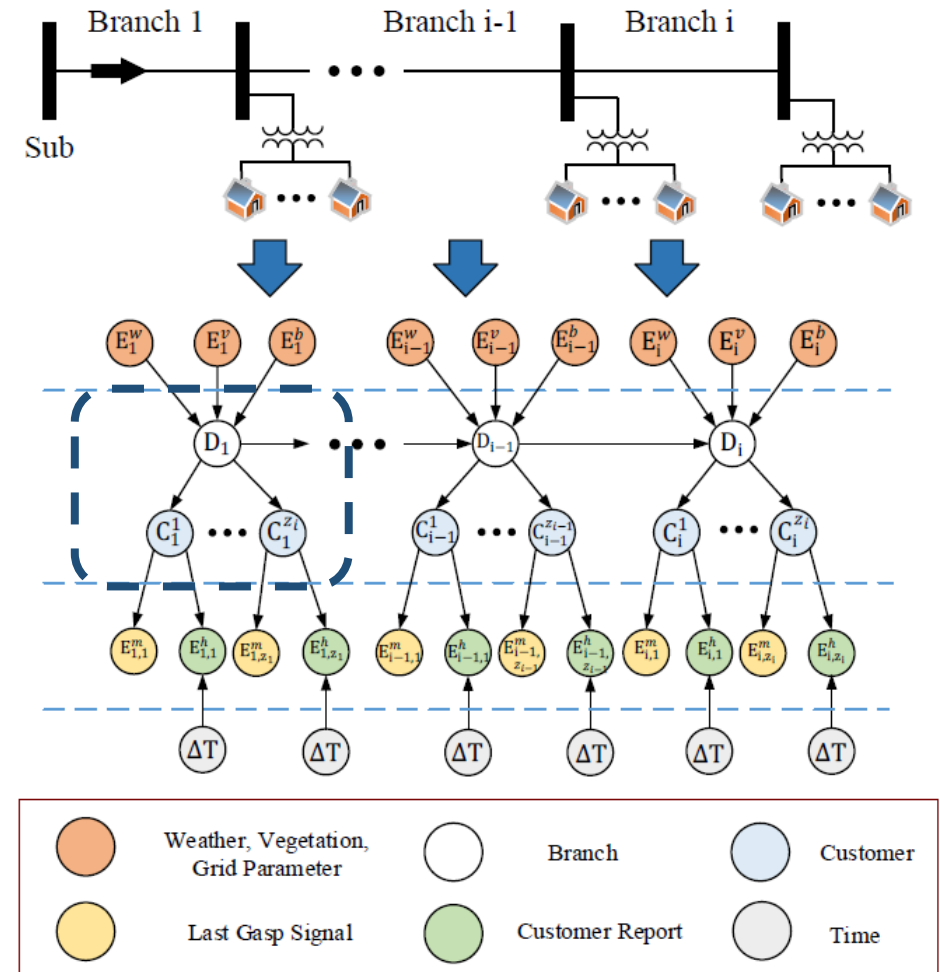


# Offline Parameter Learning and Online Inference in Graphical Models

Each edge in the constructed graph has a *parameter* that quantifies the probabilistic relationship between its parent and child nodes. A parameter is the conditional probability of *effect*  $A$ , given the value of *cause*  $B$ , represented as  $P_{A|B}(a|b)$ .

(1)  $P_{C_j^i|D_i}(c_j^i|d_i)$  : the chance of de-energization of customer if the state of its parent branch is known

- If parent branch is outaged, then customer is certainly outaged.
- If the branch is energized, the customer could still be outaged as a result of the customer's own failures, regardless of the states of the neighbor customers.
- The parameter is learned empirically from historic data.

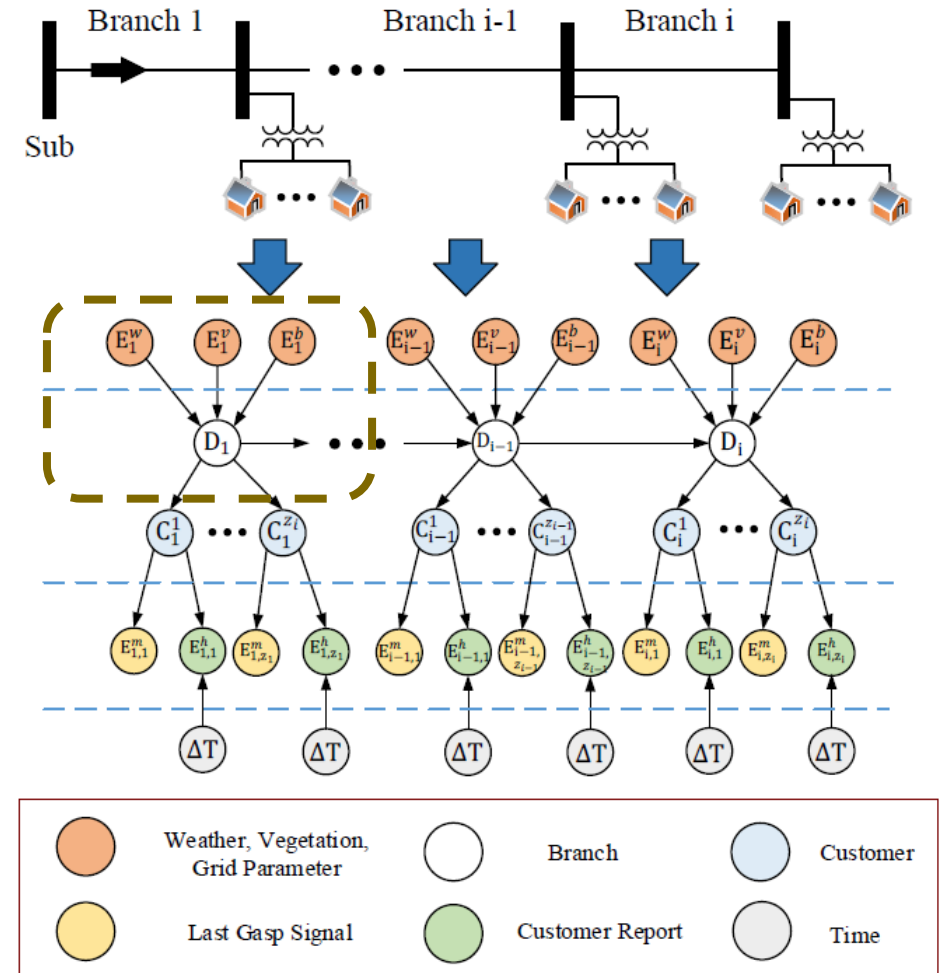




# Offline Parameter Learning and Online Inference in Graphical Models

(2)  $P_{D_i|D_{i-1}, E_i^w, E_i^v, E_i^b}(d_i|d_{i-1}, e_i^w, e_i^v, e_i^b)$  : the chance of de-energization for a child branch if the state of its parent branch is known

- If the feeder is interrupted at any arbitrary node before node  $i$ , we can automatically conclude that  $D_i = 1$ , regardless of the values of the other variables.
- If the parent branch is energized, the child branch may still be de-energized due to the branch's own failure (i.e.,  $P_i^f$ ).
- To deal with data scarcity, a fragility model is utilized to estimate  $P_i^f$  based on wind speed  $e_i^w$ , vegetation information  $e_i^v$ , and grid parameters  $e_i^b$  [7].
- **Fragility mode:** a series model with the fragility analysis of each pole and conductor within the individual branch.



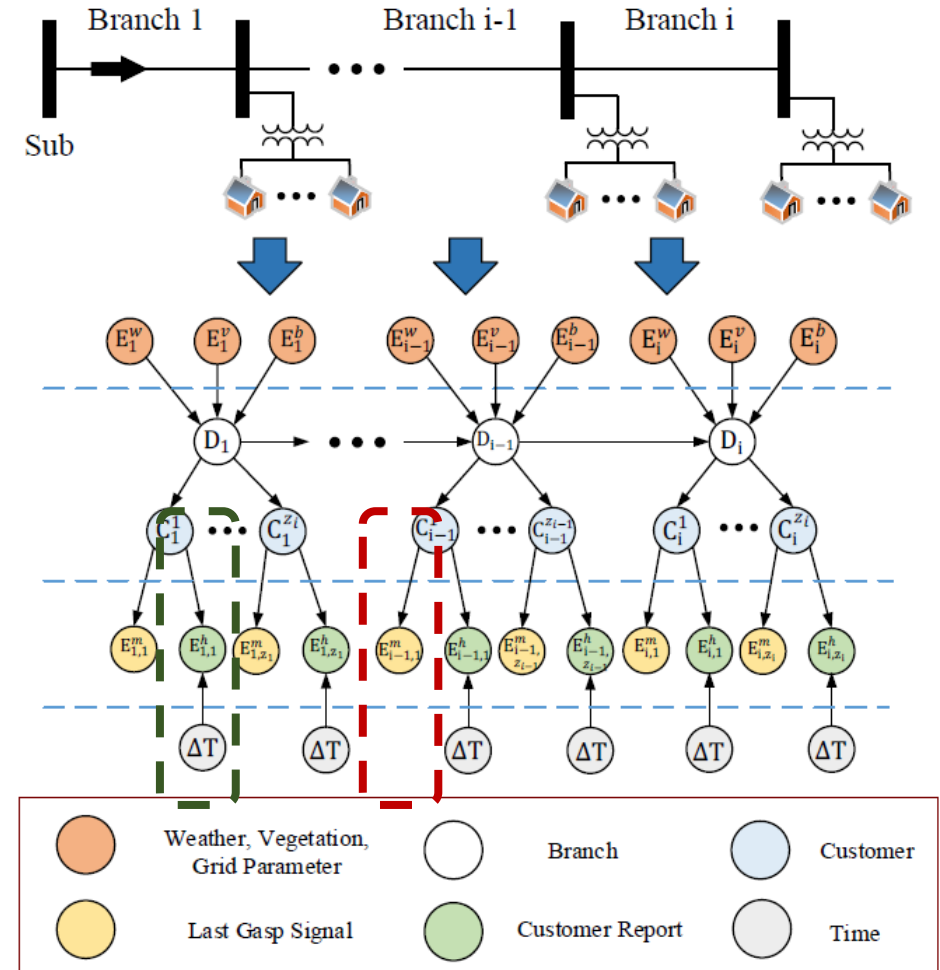
# Offline Parameter Learning and Online Inference in Graphical Models

(3)  $P_{E_{i,j}^h | C_i^j, \Delta T} (e_{i,j}^h | c_i^j, \Delta t)$  : the probability of receiving human-based evidence (i.e., customer call and social media) if the state of the corresponding customer is known

- $\Delta T$ : waiting time of outage location inference (i.e., 10 minutes).
- When  $\Delta T$  increases, utilities can receive more human-based evidence.
- This CDF is formulated using an exponential distribution. The parameter is learned empirically from historic data.

(4)  $P_{E_{i,j}^m | C_i^j} (e_{i,j}^m | c_i^j)$  : the probability of receiving meter-evidence (i.e., last gasp signal) if the state of the corresponding customer is known, which depends system observability and SM accuracy levels.

- Delivered instantaneously.
- The parameter is learned empirically from historic data.



# Offline Parameter Learning and Online Inference in Graphical Models

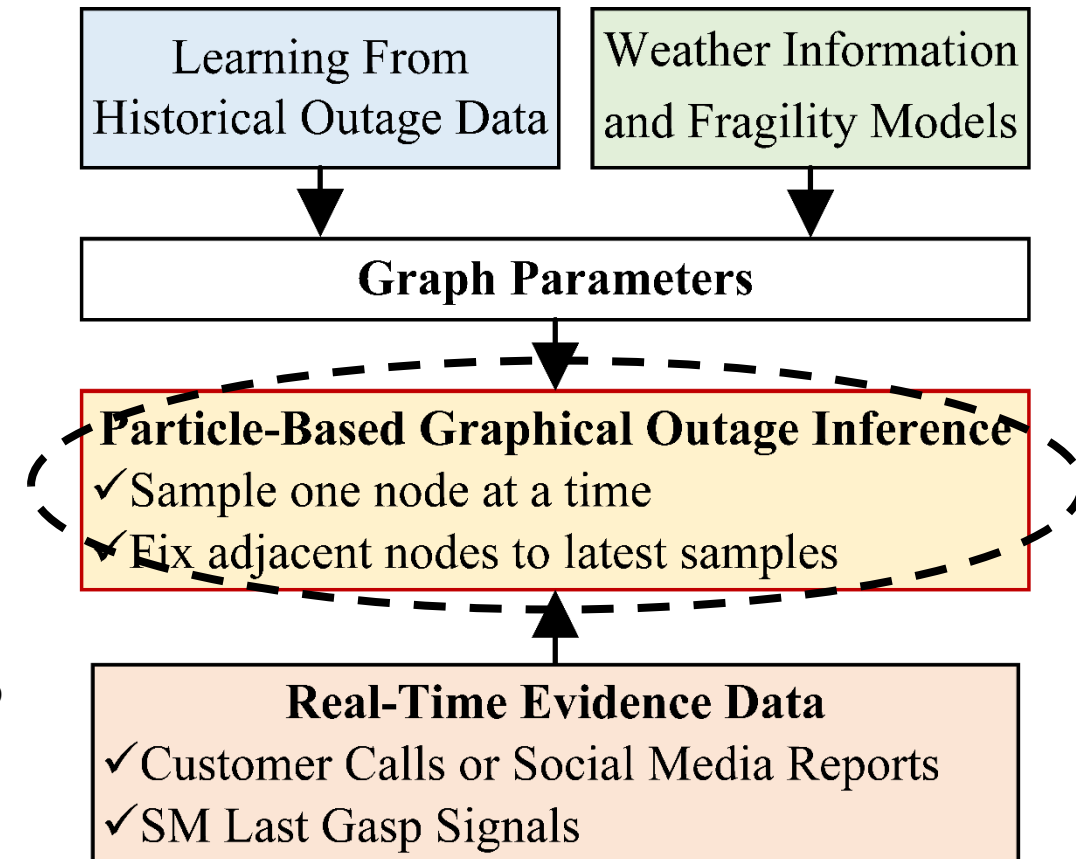
- In general, Eq. 1 can be directly solved by applying chain rule to graph parameters, as follows:

$$\begin{aligned}
 & P_{D,C|E}(\mathbf{d}, \mathbf{c}|\mathbf{e}) \\
 &= \frac{\prod P_{D_i|D_{i-1}, E_i^w, E_i^v, E_i^b}(\mathbf{d}_i|\mathbf{d}_{i-1}, \mathbf{e}_i^w, \mathbf{e}_i^v, \mathbf{e}_i^b) \prod P_{C_j^i|D_i}(\mathbf{c}_j^i|\mathbf{d}_i) \prod P_{E_{i,j}^h|C_i^j, \Delta T}(\mathbf{e}_{i,j}^h|\mathbf{c}_i^j, \Delta t) \prod P_{E_{i,j}^m|C_i^j}(\mathbf{e}_{i,j}^m|\mathbf{c}_i^j)}{\sum_i \sum_k \{ \prod P_{D_i|D_{i-1}, E_i^w, E_i^v, E_i^b}(\mathbf{d}_i|\mathbf{d}_{i-1}, \mathbf{e}_i^w, \mathbf{e}_i^v, \mathbf{e}_i^b) \prod P_{C_j^i|D_i}(\mathbf{c}_j^i|\mathbf{d}_i) \prod P_{E_{i,j}^h|C_i^j, \Delta T}(\mathbf{e}_{i,j}^h|\mathbf{c}_i^j, \Delta t) \prod P_{E_{i,j}^m|C_i^j}(\mathbf{e}_{i,j}^m|\mathbf{c}_i^j) \}} \quad (3)
 \end{aligned}$$

- This approach takes advantage of the conditional independence inherent in the graphs, rather than simply assuming full independence as with the pooling method.
- Instead of a brute-force enumeration of all possible  $\{D,C\}$  values from scratch, the proposed graphical technique relies on graph parameters to decompose  $P_{D,C|E}(\mathbf{d}, \mathbf{c}|\mathbf{e})$ , which leads to an exponential reduction in outage detection time.

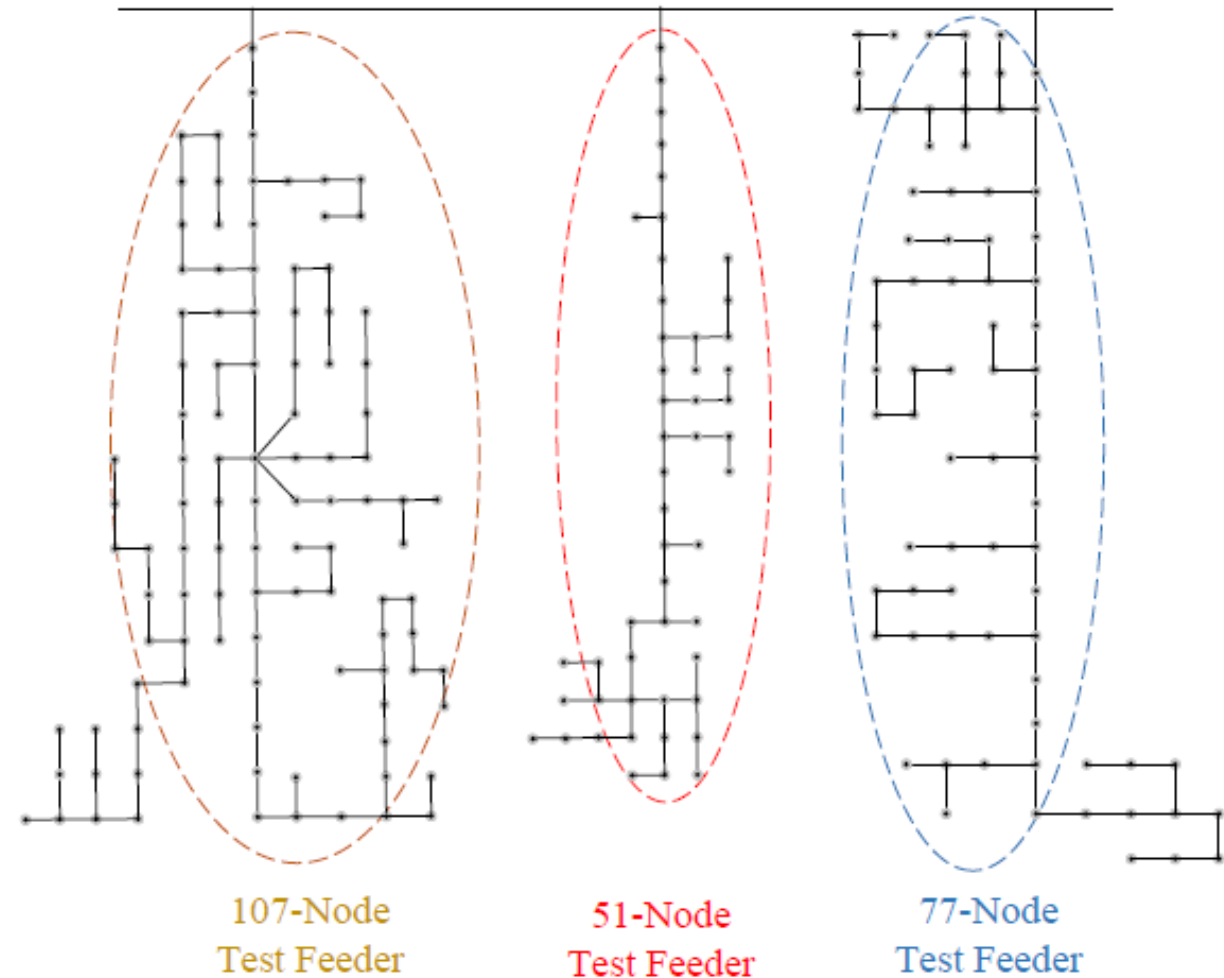
# Offline Parameter Learning and Online Inference in Graphical Models

- **Challenge:** solving Eq. 3 requires running computationally expensive summation operations over all nodes of the graph simultaneously, which is not scalable for large distribution grids.
- **Solution:** Using fast particle-based inference methods, such as Gibbs sampling [7], to perform graphical inference efficiently.
- Particle-based methods sample from individual nodes in the graph repeatedly at each iteration while fixing all the others to their latest samples.
- The key idea is to limit computation to a single node at each step while still considering nodal interdependence, which enables immense acceleration of outage inference in large grids.



# Numerical Results

- Tested on three real distribution feeders, 51-, 77-, and 107-node test feeders.
- Evaluated the proposed method under three different observability levels, 25%, 50%, 75% for each test feeder.
- Generate 1500 outages for each case (a total of 9 cases).
- In each outage, the outage location is randomly chosen.
- The amount and location of meter-based evidence in each scenario is determined system observability.
- The human-based evidence is generated using a pre-defined exponential PDF (different from (3)) given  $\Delta T=10$  minutes.

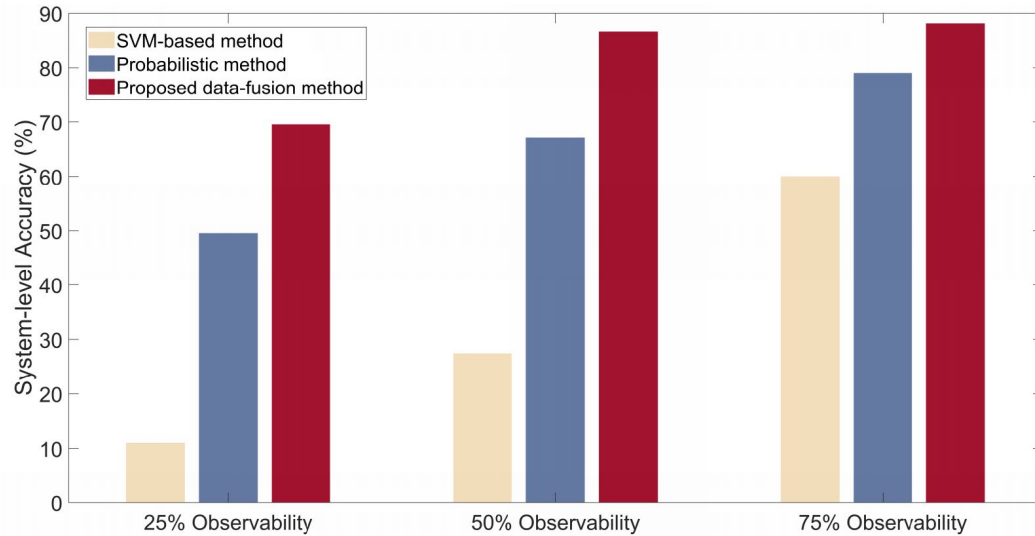


# Numerical Results

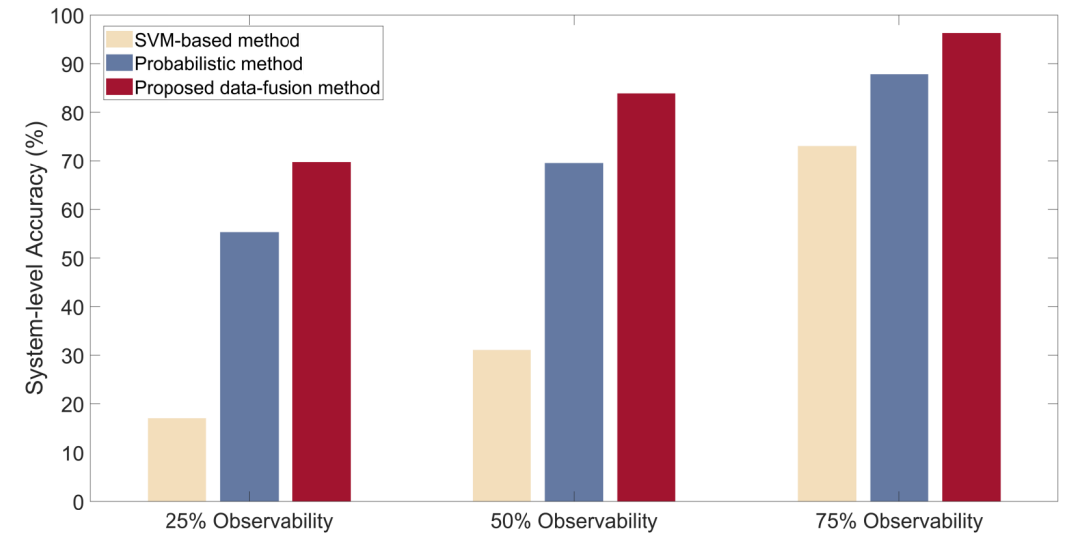
| System Name          | Observability | Branch-level Accuracy | Branch-level Precision | Branch-level Recall | Branch-level $F_1$ | Location Accuracy |
|----------------------|---------------|-----------------------|------------------------|---------------------|--------------------|-------------------|
| 51-Node Test Feeder  | 25%           | 99.05%                | 86.48%                 | 99.56%              | 90.65%             | 69.73%            |
|                      | 50%           | 99.65%                | 92.77%                 | 99.82%              | 95.07%             | 83.93%            |
|                      | 75%           | 99.89%                | 98.38%                 | 100%                | 98.93%             | 96.33%            |
| 77-Node Test Feeder  | 25%           | 98.7%                 | 83.47%                 | 98.88%              | 88.05%             | 69.5%             |
|                      | 50%           | 99.41%                | 92.43%                 | 98.86%              | 94.32%             | 86.6%             |
|                      | 75%           | 99.60%                | 92.82%                 | 99.89%              | 95.24%             | 88.1%             |
| 106-Node Test Feeder | 25%           | 98.92%                | 83.91%                 | 99.05%              | 88.61%             | 69.6%             |
|                      | 50%           | 99.58%                | 91.11%                 | 99.54%              | 94.1%              | 80.9%             |
|                      | 75%           | 99.92%                | 98.19%                 | 100%                | 98.88%             | 92.6%             |

- ✓ Observability is determined by the number of SMs.
- ✓ The performance of the proposed outage location method improves as the observability increases, due to the high confidence levels of meter-based evidence.
- ✓ The proposed algorithm shows almost the same level of performance over the different test networks.

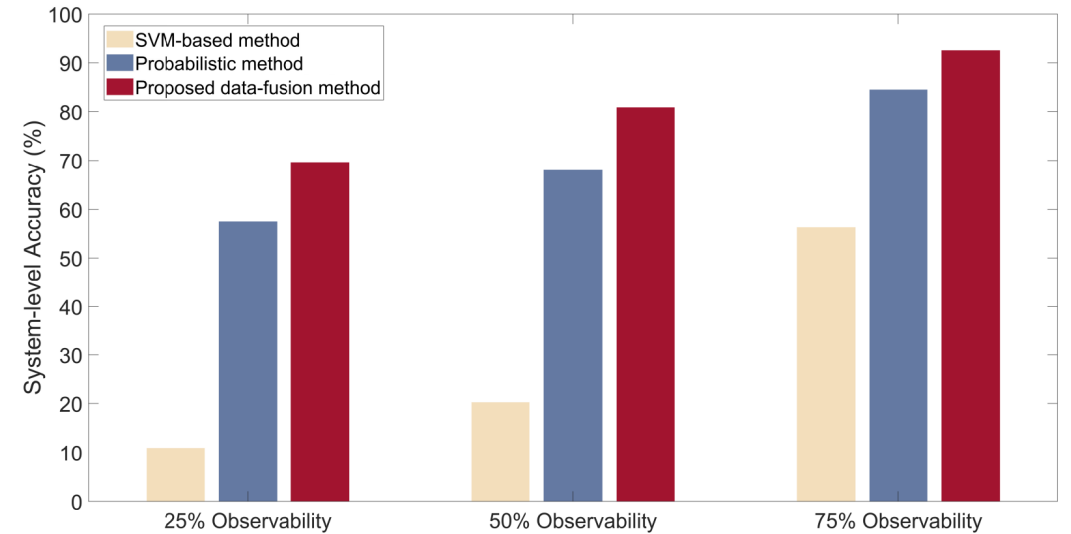
# Numerical Results



Comparison results of the 77-node test system



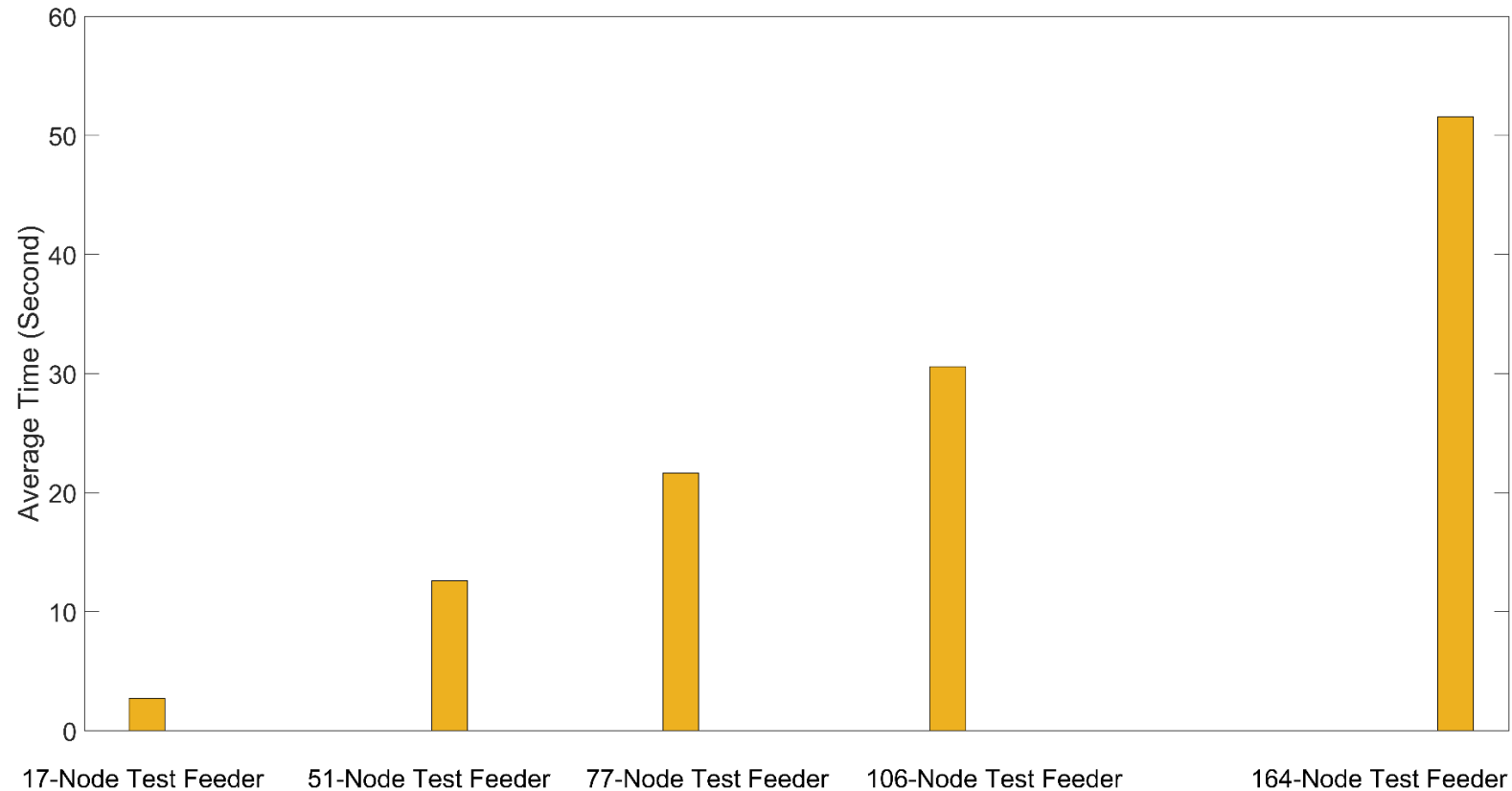
Comparison results of the 51-node test system



Comparison results of the 106-node test system

- ✓ Compared with two existing outage location methods, a SVM-based approach [8] and a probabilistic approach [9].
- ✓ [9] and our method generally outperform [8], especially for system with low observability.
- ✓ Among the data fusion-based methods, our method performs better than [9] because the proposed method not only uses data from smart meters, but also effectively combines data from non-metered data sources.

# Numerical Results



- ✓ Conducted on two additional real-world distribution feeders: a 17-node and 164-node feeders to provide a comprehensive computational complexity analysis.
- ✓ Using our method, the average computational time for outage location has an approximately linear, rather than exponential, relationship with the size of the distribution grid.



# Conclusions

- Combining heterogenous data sources can significantly improve outage detection accuracy.
- Outage data sources are conditionally independent.
- Our method encodes the network's topology and the causal relationship between outage evidence and branch states into BNs by leveraging the conditional independence inherent in distribution grids.
- The proposed graphical method, by the merit of its multi-source nature, is highly robust against low observability, while at the same time maintaining high detection speed.
- Future study will seek to extend the proposed method in meshed grids with high penetration distributed energy resources.

# References

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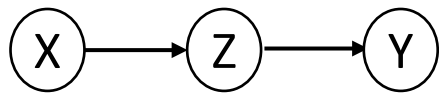
# Thank you!

## Q&A

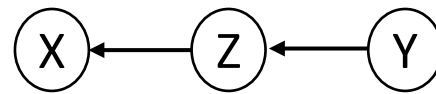
# Encoding Distribution Grids and Data into Probabilistic Graphs

✓ The edge directions are important.

➤ Variable Z is cause of Y and effect of X. In (b), variable Z is a common effect for both X and Y.



(a) Causal Chain



(b) Common Effect

➤ For (a), X cannot influence Y via Z if Z is observed.

➤ For (b), X can influence Y via Z, but only if Z is not observed.

